

# Servo solenoid valves with electrical position feedback (Lvdt DC/DC ±10 V)

# Type AL 4WRPH10

Size 10 Unit series 2X Maximum working pressure P, A, B 315 bar, T 250 bar Nominal flow rate 50...100 l/min ( $\Delta p$  70 bar)

### List of contents

### **Contents** Page **Features** Ordering data and scope of delivery 2 2 Preferred types Function, sectional diagram 3 Symbols 3 Technical data Valve with external trigger electronics 5 and 6 Performance curves 7 and 8 Unit dimensions

# **Features**

Directly operated servo solenoid valve NG10, with control piston and sleeve in servo quality
 Actuated on one side, 4/4 fail-safe position when switched off
 Control solenoid with integral position feedback and electronics for position transducer (Lvdt DC/DC)
 Suitable for electrohydraulic controllers in production and testing systems
 For subplate attachment, mounting hole configuration to ISO 4401-05-04-0-94
 Subplates as per catalogue section RE 45055 (order separately)
 Line sockets to DIN 43560-AM2

Solenoid 2P+PE/M16 x 1.5, position transducer 4P/Pg7

- External trigger electronics (order separately)

### Variants on request

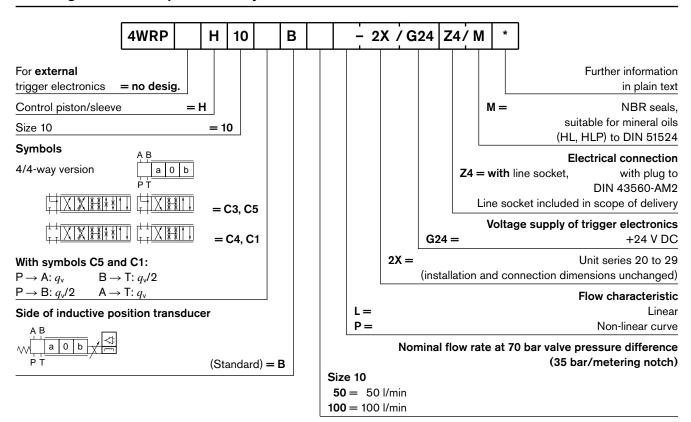
- For standard applications

in scope of delivery

- Special symbols for plastic injection-moulding machines
- Sturdy "ruggedized" version for applications up to 40 g, valve with metal cap and central plug (7P).

1/10

# Ordering data and scope of delivery



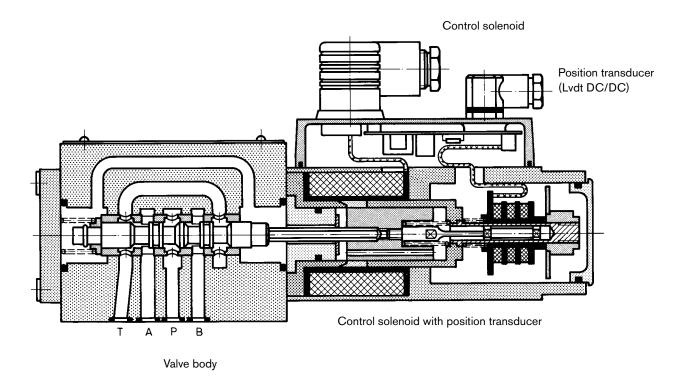
# Preferred types (available at short notice)

Type 4WRPH 10	
C3/C5	
4WRPH 10 C3B50L -2X/G24Z4 / M	
4WRPH 10 C3B100L -2X/G24Z4 /M	
4WRPH 10 C5B100L -2X/G24Z4 /M	
4WRPH 10 C3B50P -2X/G24Z4 /M	
4WRPH 10 C3B100P -2X/G24Z4 /M	
4WRPH 10 C5B100P -2X/G24Z4 /M	

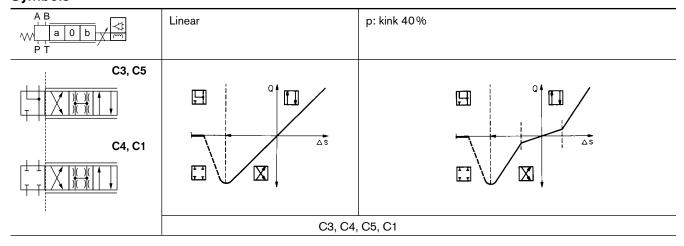
Type 4WRPH10	
C1/C4	
4WRPH 10 C4B50L -2X/G24Z4 /M	
4WRPH 10 C4B100L -2X/G24Z4 /M	
4WRPH 10 C1B100L -2X/G24Z4 /M	
4WRPH 10 C4B50P -2X/G24Z4 / M	
4WRPH 10 C4B100P -2X/G24Z4 /M	
4WRPH 10 C1B50P -2X/G24Z4 /M	
4WRPH 10 C1B100P -2X/G24Z4 /M	

# Function, sectional diagram

# Servo solenoid valve 4WRPH 10



# **Symbols**



# **Technical data**

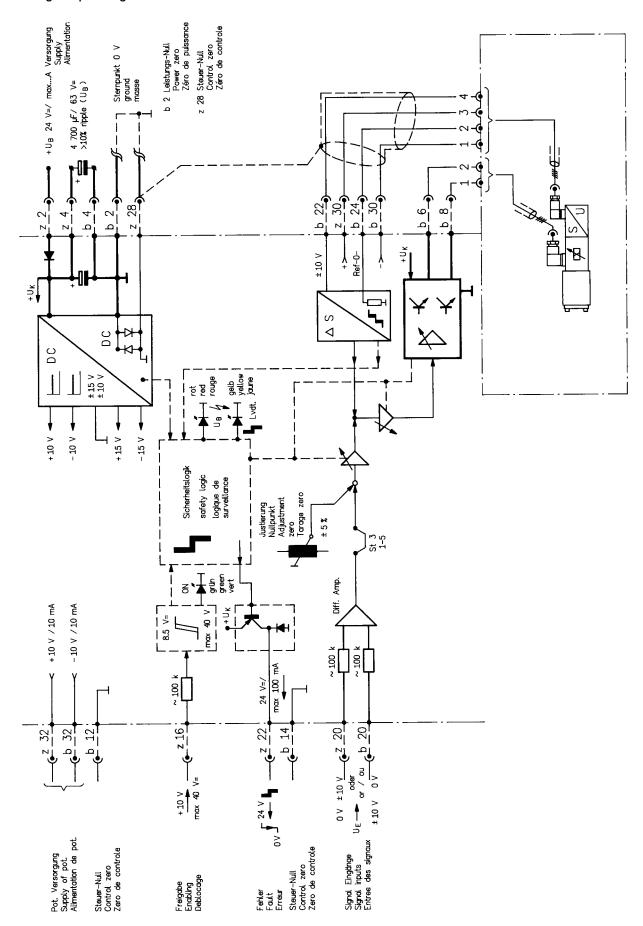
recinical data							
General							
Construction							
Actuation		Proportional solenoi	Proportional solenoid with position control, external amplifier				
Type of mounting		Subplate, mounting hole configuration NG10 (ISO 4401-05-04-0-94)					
Installation position		Optional					
Ambient temperature range	°C	-20+50					
Weight	kg	6.8					
Vibration resistance, test condition	3 2						
Hydraulic (measured with HI							
Pressure fluid	, 0	Hydraulic oil to DIN	51524 .	535, other	fluids after prior	consultation	
Viscosity range recommended	mm²/s	20100					
max. permitted	mm²/s	10800					
Pressure fluid temperature range	°C	-20+80					
Maximum permissible degree of		Class 18/16/13 <sup>1)</sup>					
contamination of pressure fluid Purity class to ISO 4406 (c)		01000 10710710					
Flow direction		See symbol					
Nominal flow at	I/min	50	50		100	100	
$\Delta p = 35$ bar per notch <sup>2)</sup>	,,,,,,,,	(1:1)	(2:1)		(1:1)	(2:1)	
Max. working pressure	bar	Port P, A, B: 315					
Max. pressure	bar	Port T: 250					
Operating limits at $\Delta p$ Pressure drop at valve	bar	315	31	5	160	160	
$q_{Vnom}$ : $> q_{N}$ valves	bar	250	25	0	100	100	
Leakage at 100 bar	cm³/min	<1200	<120	0	<1500	<1000	
+	cm <sup>3</sup> /min	<600	<50	00	<600	<600	
Electrical		I					
Cyclic duration factor	%	100					
Power supply		24 V <sub>nom</sub> (external am	plifier)				
Degree of protection		IP 65 to DIN 40050					
Solenoid connector		Connector DIN 43650/ISO 4400 M16x1.5 (2P+PE)					
Position transducer connector		Connector Pg7 (4P)					
Max. solenoid current	Α	3.7					
Coil resistance $R_{20}$	Ω	2.4					
Max. power consumption at 100% load and operational temperature	ó VA	60					
Position transducer DC/DC technology		Supply: +15 V/35 mA Signal: 0±10 V ( $R_L \ge 10 \text{ k}\Omega$ )					
Static/Dynamic							
Hysteresis	%	≦ 0.2					
Manufacturing tolerance for $q_{\text{max.}}$	%	< 10					
Response time for signal change 0100%	ms	< 25					
Thermal drift		Zero point displacer	nent <1	% at $\Delta T = 40$	 )°C		
<del></del>							

<sup>&</sup>lt;sup>1)</sup> The purity classes stated for the components must be complied with in hydraulic systems. Effective filtration prevents problems and also extends the service life of components.

 $<sup>^{2)}</sup>$  Flow rate at a different  $\Delta p$   $q_{\rm x} = q_{\rm nom} \cdot \sqrt{\frac{\Delta p_{\rm x}}{35}}$ 

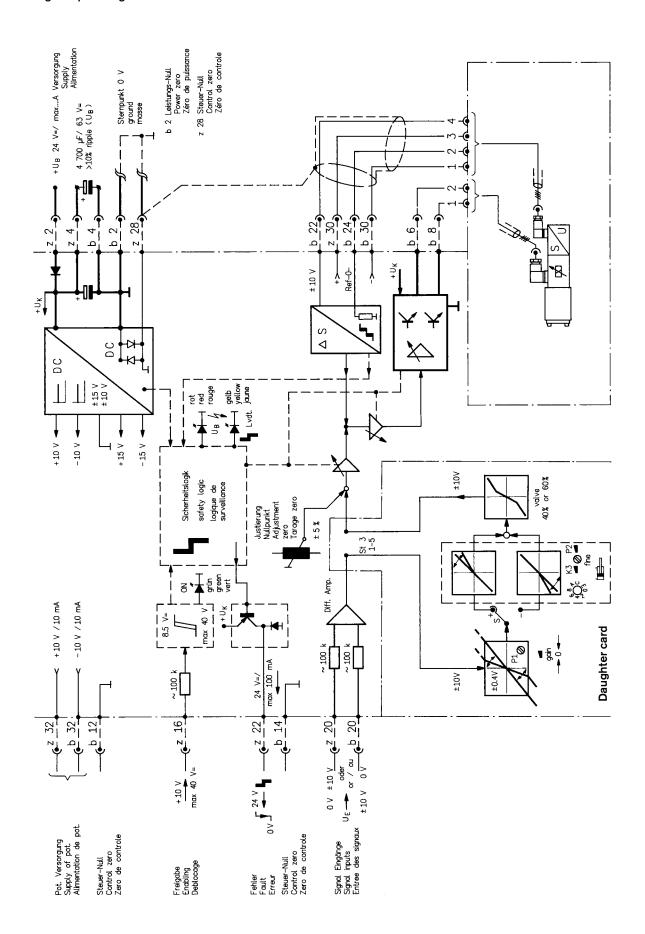
# Valve with external trigger electronics (standard linear curve: L)

### Block diagram/pin assignment



# Valve with external trigger electronics (standard non-linear curve: P)

### Block diagram/pin assignment



# **Performance curves** (measured with HLP46, $\vartheta_{oil} = 40 \,^{\circ}\text{C} \pm 5 \,^{\circ}\text{C}$ )

### Flow rate/Signal function

 $Q = f(U_E)$ 

L: Linear

Q %

100

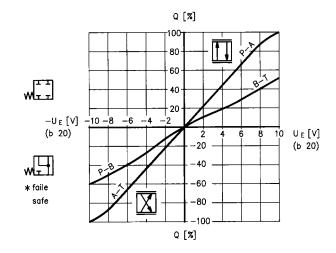
80

-UE [V] -10 -8 -6 -4 -2 2 4 6 8 10 UE [V] (b20)

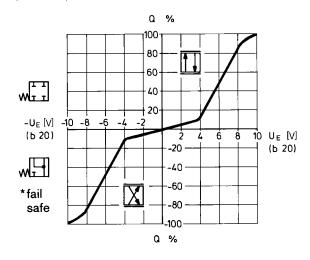
\*fail safe

Q %

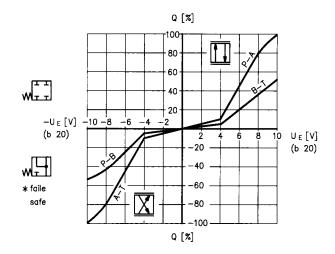
L: (linear) 2:1



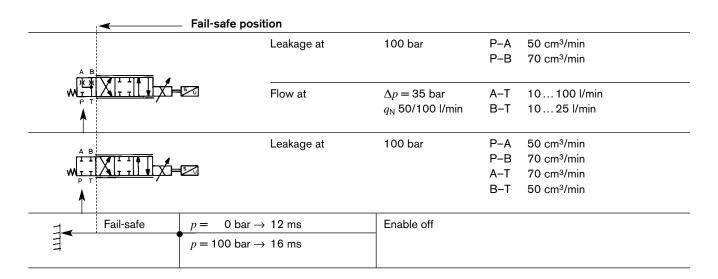
P: (kink 40%)\*\*



P: (kink 40%) 2:1\*\*



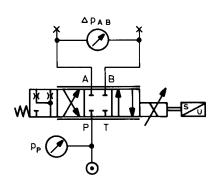
<sup>\*\*</sup> $Q_{N}$ -kink = 10 %  $Q_{N}$ .

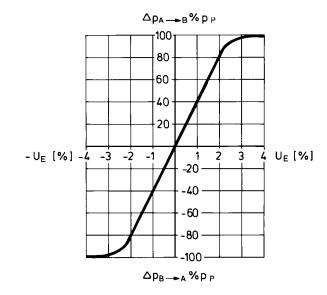


<sup>\*</sup>Fail-safe when enabling is not released.

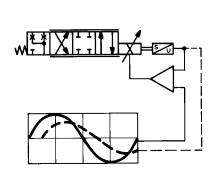
# Performance curves (measured with HLP46, $\vartheta_{\text{oil}} = 40\,^{\circ}\text{C} \pm 5\,^{\circ}\text{C}$ )

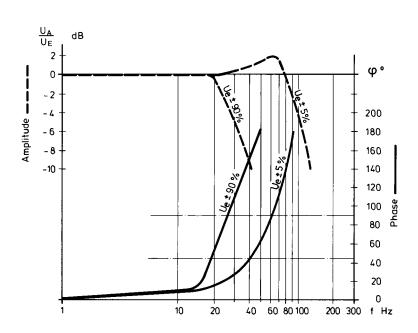
# Pressure gain



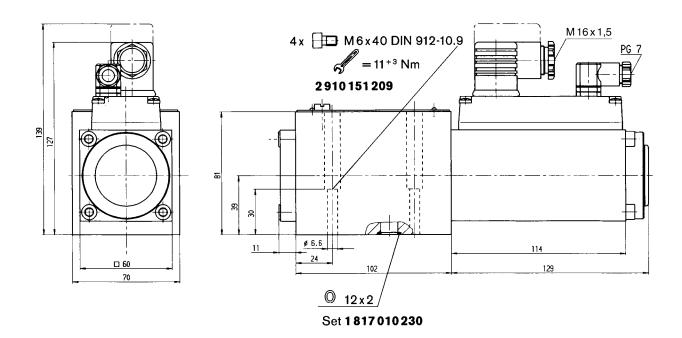


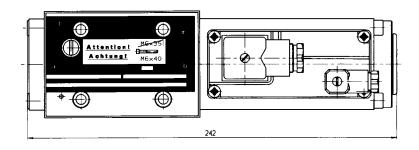
### Bode diagram

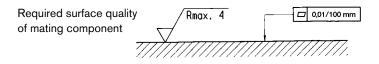




# Unit dimensions (nominal dimensions in mm)

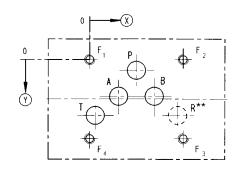






Mounting hole configuration: NG10

(ISO 4401-05-04-0-94)



- 1) Deviates from standard
- <sup>2)</sup> Thread depth: Ferrous metal 1.5 x Ø\* Non-ferrous 2 x Ø
- \* (NG10 min. 10.5 mm)

	Р	Α	Т	В	F <sub>1</sub>	F <sub>2</sub>	F <sub>3</sub>	F <sub>4</sub>	R
<b>⊗</b>	27	16.7	3.2	37.3	0	54	54	0	50.8
<b>(</b> Y)	6.3	21.4	32.5	21.4	0	0	46	46	32.5
Ø	10.5 <sup>1)</sup>	10.5 <sup>1)</sup>	10.5 <sup>1)</sup>	10.5 <sup>1)</sup>	M6 <sup>2)</sup>	M6 <sup>2)</sup>	M6 <sup>2)</sup>	M6 <sup>2)</sup>	10.5 1)

\*\* 5/3 - NG10

 $R = P_2$